Generative models for human motion

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Introduction

This work aims to tackle the problem of generating realistic and diverse human motion sequences from highly semantic textual descriptions. We aim to develop a model that can interpret the prompts being fed and generate believable motions that were not part of the training set. We are using an adapted version of the generative variational autoencoder proposed in [1], combined with a language encoder/model (currently CLIP [2]), and training on the highly annotated motion capture dataset BABEL [3]. This generated motion is then fed through a kinematic model to improve the results and realism.

Contributions

We plan to fully mesh the resulting character, and integrate hand movement in the generated motion, which is often overlooked. Furthermore, we intend to implement physical constraints in our model that will hopefully improve the realism and allow for object and scene interaction.

Methods

- Motion and text are encoded onto latent space
- Both used for training; only text is used for testing
- Generated motion is sampled from latent space
- Generated motion is fine-tuned using physical constraints, adding kinematic models to latent spaces



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Fig. 1: Overview of the current model under analysis, where motion and text are encoded into the latent space at training time. At test time, only the language branch is used to sample from the latent space and generate the motion. Adapted from [4].

References

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